

BotPlatform SDK User Guide

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1 Support

1.1 Contact us

You can always contact us for technique support by the following ways:

E-MAIL	support@botplatform.com
Address	http://botplatform.com

1.2 Forum

You can also post questions to our forum, and we will reply as soon as possible.

Url of our forum: <http://botplatform.uservice.com/>

1.3 Other documentation

BotPlatform API has been well documented in several program languages (including java, vc++, c#, vb, etc.) which can help you to find answers.

2 Architecture

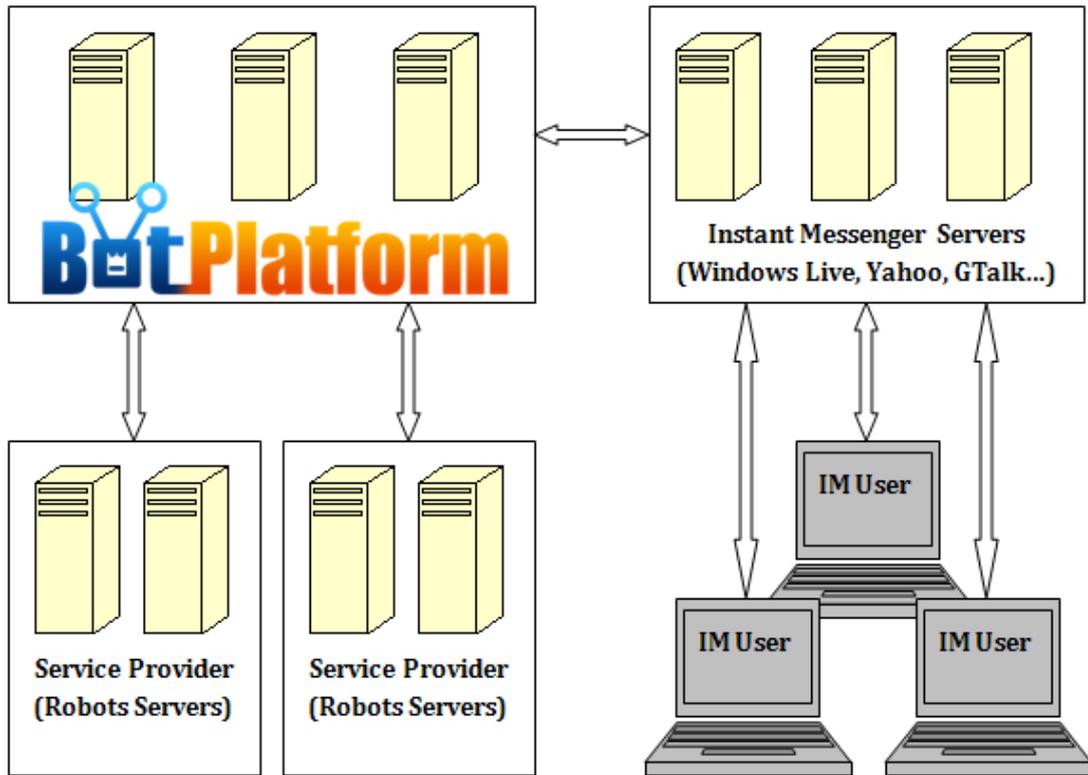


Figure 1

As shown in Figure 1, the whole BotPlatform involves Service Providers (SP), BotPlatform Servers (BPS), IM Server, and IM User client, whose relations are shown as follows:

- * SPs connect to BPs to provide service;
- * IM User clients connect to IM Server for IM service;
- * The BotPlatform Server is the key that connects the SPs to IM User clients. You can take BotPlatform as an adapter from BotPlatform API to IM protocol API (ex: MSN, Yahoo, GTalk, etc.). So it's transparent for the SPs to interact with IM User clients.

SPs can have their own service servers which connect to BotPlatform Server by our SDK. When one service server meets some bottleneck, SP can balance your burden by running your service in several parallel service servers; In the meantime, BotPlatform will guarantee the stability of network (both SP-BP and BP-MSN Server).

The bots (SPs) log on as IM client by BotPlatform, and will be kept online at BotPlatform. So SP should never care about this part.

3 Development Flow

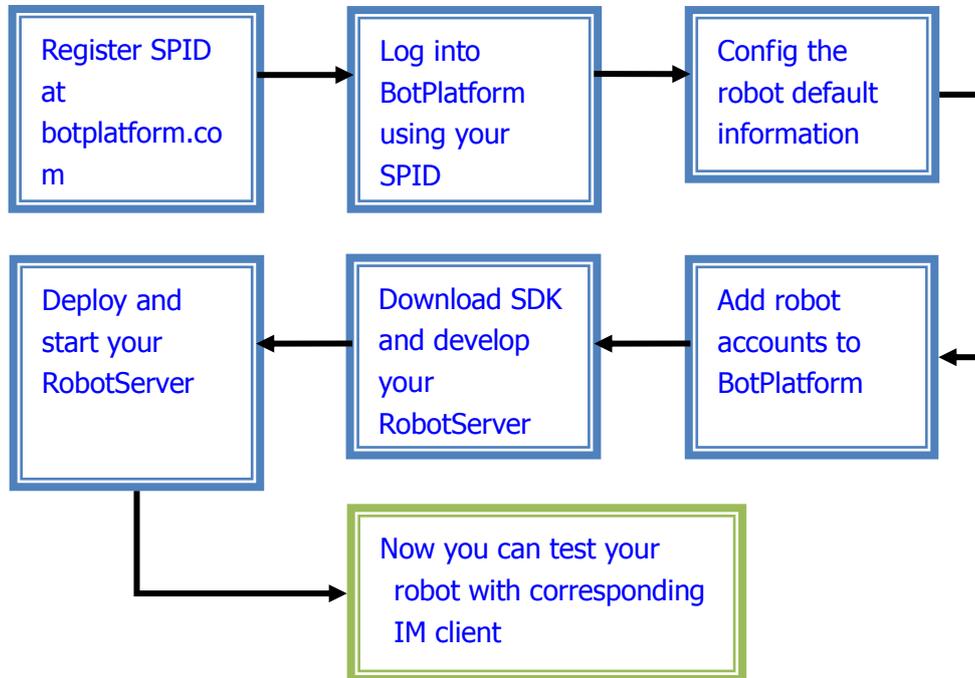


Figure 2

3.1 Register SPID at botplatform.com

Go to the SP website(<http://botplatform.com>) for registration



Figure 3

After registration, BotPlatform will issue a SPID as the login account.



Figure 4

3.2 Log into BotPlatform using your SPID

Log into BotPlatform using your SPID and password

After you logged in, you will see the BotPlatform administration system.

The system consists of the following modules:

* Management

- Manage your the basic information and the robot default information.

*SP Resource

- Manage your robots' resources such as display picture, emoticon ,etc..

*User resource

- This module is a temporary store of your friends' resources. You can check out these resource if you want.

*Download

- This module provide you with various version of SDKs downloading.

*Documentation

- Useful documents for developing.

3.3 Config the robot default information

The screenshot shows the BotPlatform interface for configuring SP Information. The left sidebar contains navigation menus for Management, SP Resource, User Resource, Download, and Documentation. The main content area is divided into two sections: SP Information and Robot Information. The SP Information section includes fields for SPID (SP106831), Account Type (Personal), Password (masked), Company Name (emily), Contact (incesoft), Telephone (60822348), Email address (incesoft006@hotmail.com), Location (China), and Province (shanghai). The Robot Information section includes fields for The Robot Default Picture (dp1.png), The Robot Default Scene (scene1.jpg), and The Robot Default Name (My Robot). Each field has a 'Change' button or is marked as '(Required)'.

Figure 5

3.4 Add robot accounts to BotPlatform

Bot account is an IM account(ex:Window live account).To add bot accounts,click the "Management"->"MSN Account Management" link in left region of the page.You will see your bot account list in right region of the page. After adding some accounts,you will see the "sign in" link in every account entry,you can click to sign in;After signing in successfully,the "sign out" link will appear instead of "sign in".

Then add the bot account signed in as your MSN buddy,you will see it in status "Away".If you connect your SP client to BotPlatform,the account will switch to status "Available".

The screenshot shows the BotPlatform Management page. The left sidebar contains navigation menus for Management, SP Resource, and User Resource. The main content area shows a list of bot accounts. The first account is 'incesoft006@hotmail.com' with links for 'contacts', 'change_password', 'delete', and 'sign_out'. The 'sign_out' link is highlighted with a red box.

Figure 6

3.5 Download SDK and develop your RobotServer

3.5.1 Language

There are four languages available:Java C# C++ VB

A、Java programs can run in Linux or window with JDK installed(version 1.5+)。

B、C# C++ VB SDK is based on COM which can only run in windows.After downloading DLL of COM,you should register in windows (regsvr32 BotPlatformSDK.dll),and then import it into your project for developping。

Besides,the COM SDK fit all language based on COM.

3.5.2 Implementation codes

See [Example codes](#) 和 [API Documentation](#)。

3.5.3 Debug

Make sure that your client has connected to internet.

You can use any developing tools to debug your program.Once you start debugging,your client will connect BotPlatform;And you will see your bot account switch its status from "Away" to "Available";Any action in your codes will be reflected in your conversation with the bot.If you stop debugging,the bot account will be "Away" again.

3.6 Deploy and start your RobotServer

After coding and testing,you can deploy your server program to any kind of physical server.And one physical server can hold several SP server;Or you can deploy them to several physical server(depends on your user amount and network traffic)。

4 Features

The following features are available by using BotPlatform SDK:

Text Message	Emoticon	Nudge	Activity
FriendlyName	Signature	Display Picture	Deluxe Display Picture
Scene	Buddy Online/Offline Event	Buddy Information Event	Wink
Ink	File Transfer	Voiceclip	Webcam
Multi-User Conversation	Push Message	Get Buddy Information	

4.1 Robot Profile

After logged into the BotPlatform website,SP can manage the bot information.For example,change the friendlyName,Personal Message and display picture of your bot.



Figure 7

4.2 Deluxe Display Picture

Size should be 98x142



Figure 8

4.3 Customized Emoticon

SP can customize their own emoticon, the effect is sth. like the following figure:



Figure 9

4.4 Scene

Scene is also available in BotPlatform SDK



Figure 10

4.5 Activity

SP can use Activity to provide some enhanced presentation. It's a simple URL, you can interact with IM Use without knowledge about Microsoft Activity SDK.



Figure 11

4.6 Wink

BotPlatform also support wink which consist of animation and sound.



Figure 12

4.7 Ink

The Ink is a feature which provide the handwriting function.



Figure 13

4.8 File Transfer



Figure 14

4.9 Voiceclip



Figure 15

5 Example codes

Check the DEMO part of SDK package for more example.

Java Example:

```
RobotServerFactory serverFactory = RobotServerFactory.getInstance();
final RobotServer server = serverFactory.createRobotServer("server.botplatform.com",
6602);
server.setReconnectedSupport(true);
server.setRobotHandler(new RobotAdapter(){
public void messageReceived(RobotSession session,
    RobotMessage message) {
    session.send("Hello World!");
    System.out.println(message.getString());
    }
});
server.login("you spid", "your sppwd");
Runtime.getRuntime().addShutdownHook(new Thread(){
    public void run(){
        server.logout();
    }
});
```

C# Example:

```
static void server_MessageReceived(IRobotSession session, IRobotMessage message)
{
    session.SendText("Hello World!");
    Console.WriteLine(message.Text);
}
static void Main(string args)
{
    RobotServerFactory serverFactory = new RobotServerFactory();
    serverFactory.Init(2);
    RobotServer server = serverFactory.CreateRobotServer("server.botplatform.com",
6602);
    server.MessageReceived += new
IRobotServerEvents_MessageReceivedEventHandler(server_MessageReceived);
    server.Login("your sppid", "your sppwd", 60000);
    string cmd = null;
    while ((cmd = Console.ReadLine()) != null)
```

```

        if (cmd.Equals("exit")) break;
server.Logout();
serverFactory.Destroy();
}

```

C++ Example:

```

ATL_FUNC_INFO s_info_onMessageReceived = { CC_STDCALL, VT_EMPTY, 2,
{ VT_UNKNOWN, VT_UNKNOWN } };
class RobotServerEventsImpl : public IDispatchImpl<1, RobotServerEventsImpl,
&DIIDIRobotServerEvents>
{
public:
    BEGIN_SINK_MAP(RobotServerEventsImpl)
        SINK_ENTRY_INFO(1, DIIDIRobotServerEvents, 3,
&RobotServerEventsImpl::onMessageReceived, &s_info_onMessageReceived)
    END_SINK_MAP()

    HRESULT stdcall onMessageReceived( IRobotSession session, IRobotMessage message )
    { session->SendText("Hello World!"); std::cout << message->Text << std::endl; return S_OK; }; int
    tmain(int argc, TCHAR argv) { CoInitializeEx(NULL, COINIT_MULTITHREADED);
    { CComPtr<IRobotServerFactory> spRobotServerFactory;
    spRobotServerFactory.CoCreateInstance( CLSID_RobotServerFactory, NULL,
    CLSCTX_INPROC ); spRobotServerFactory->Init( 2 );

        IRobotServerPtr spRobotServer =
    spRobotServerFactory->CreateRobotServer( "server.botplatform.com", 6602 );

        RobotServerEventsImpl eventImpl;

        eventImpl.DispatchEventAdvise( spRobotServer );

        spRobotServer->Login( "your spid", "your sppwd", 60000 );

        std::string cmd;

        while( true )
        {

            std::cin >> cmd;

```

```

        if ( cmd == "exit" )

            break;

        }

        spRobotServer->Logout();

        spRobotServerFactory->Destroy();

    }

    CoUninitialize();

    return 0;

}

```

VB Example:

```

Sub MessageReceived(ByVal session As IRobotSession, ByVal message As
IRobotMessage)
    session.SendText("Hello World!")
    Console.WriteLine(message.Text)
End Sub
<MTAThread(> Sub Main()
    Dim robotServerFactory As RobotServerFactory = New
RobotServerFactory    robotServerFactory.Init(2)

    Dim robotServer As RobotServer = robotServerFactory.CreateRobotServer("server.botplatform.com",
6602)

    AddHandler robotServer.MessageReceived, AddressOf MessageReceived    robotServer.Login("your
spid", "your sppwd", 60000)

    Dim cmd As String = ""

    Do While cmd <> "exit"

```

```
cmd = Console.ReadLine()
```

```
Loop
```

```
robotServer.Logout()
```

```
robotServerFactory.Destroy()
```

```
End Sub
```